

CP1 Chapter 6

Matrices

Chapter Overview

1. Understand matrices and perform basic operations (adding, scalar multiplication)
2. Multiply Matrices
3. Find the determinant or inverse of a matrix
4. Solve simultaneous equations using matrices

3 Matrices	3.1	Add, subtract and multiply conformable matrices. Multiply a matrix by a scalar.	
	3.2	Understand and use zero and identity matrices.	

3 Matrices <i>continued</i>	3.3	<p>Use matrices to represent linear transformations in 2-D.</p> <p>Successive transformations.</p> <p>Single transformations in 3-D.</p>	<p>For 2-D, identification and use of the matrix representation of single and combined transformations from: reflection in coordinate axes and lines $y = \pm x$, rotation through any angle about $(0, 0)$, stretches parallel to the x-axis and y-axis, and enlargement about centre $(0, 0)$, with scale factor k, ($k \neq 0$), where $k \in \mathbb{R}$.</p> <p>Knowledge that the transformation represented by AB is the transformation represented by B followed by the transformation represented by A.</p> <p>3-D transformations confined to reflection in one of $x = 0$, $y = 0$, $z = 0$ or rotation about one of the coordinate axes.</p> <p>Knowledge of 3-D vectors is assumed.</p>
	3.4	Find invariant points and lines for a linear transformation.	For a given transformation, students should be able to find the coordinates of invariant points and the equations of invariant lines.
	3.5	Calculate determinants of 2×2 and 3×3 matrices and interpret as scale factors, including the effect on orientation.	Idea of the determinant as an area scale factor in transformations.
	3.6	<p>Understand and use singular and non-singular matrices.</p> <p>Properties of inverse matrices.</p> <p>Calculate and use the inverse of non-singular 2×2 matrices and 3×3 matrices.</p>	<p>Understanding the process of finding the inverse of a matrix is required.</p> <p>Students should be able to use a calculator to calculate the inverse of a matrix.</p>

3 Matrices <i>continued</i>	3.7	Solve three linear simultaneous equations in three variables by use of the inverse matrix.	
	3.8	Interpret geometrically the solution and failure of solution of three simultaneous linear equations.	<p>Students should be aware of the different possible geometrical configurations of three planes, including cases where the planes,</p> <p>(i) meet in a point</p> <p>(ii) form a sheaf</p> <p>(iii) form a prism or are otherwise inconsistent</p>

Introduction

A matrix (plural: matrices) is **simply an 'array' of numbers**, e.g.

$$\begin{pmatrix} 1 & 0 & -2 \\ 3 & 3 & 0 \end{pmatrix}$$

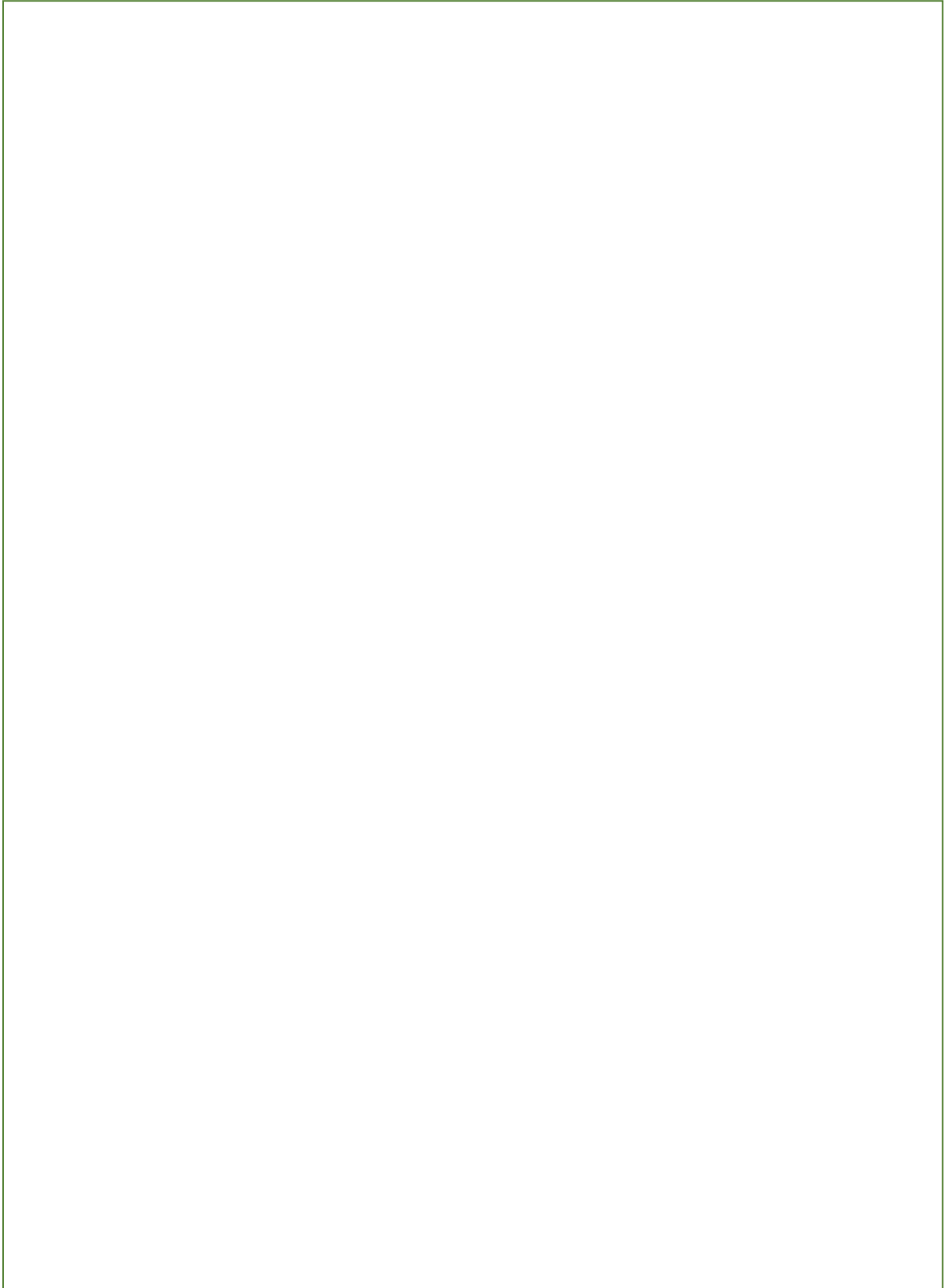
On a simple level, a matrix is just a way to organise values into rows and columns, and represent these multiple values as a single structure.

The dimension of a matrix is its **size**, in terms of its number of **rows** and **columns** (in that order).

Examples:

Matrix	Dimension
$\begin{pmatrix} 1 & 3 & -7 \\ 4 & 0 & 5 \end{pmatrix}$	
$\begin{pmatrix} 1 \\ 6 \\ -3 \end{pmatrix}$	
$(1 \quad 6 \quad 0)$	

Matrix Fundamentals



Operations with Matrices

1. Addition and subtraction

2. Scalar Multiplication