## Lower 6 Chapter 11

## Vectors

## Chapter Overview

1. Add/scale factors and show vectors are parallel.
2. Calculate magnitude and direction of a vector.
3. Understand and use position vectors.
4. Solve geometric problems.
5. Understand speed vs velocity.

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## Vectors

| 9.1 | Use vectors in two <br> dimensions. | Students should be familiar with column <br> vectors and with the use of $\mathbf{i}$, and $\mathbf{j}$ unit <br> vectors. |
| :--- | :--- | :--- |
| 9.2 | Calculate the magnitude and <br> direction of a vector and <br> convert between component <br> form and <br> magnitude/direction form. | Students should be able to find a unit vector <br> in the direction of a, and be familiar with the <br> notation $\|\mathbf{a}\|$ |
| 9.3 | Add vectors <br> diagrammatically and <br> perform the algebraic <br> operations of vector addition <br> and multiplication by scalars, <br> and understand their <br> geometrical interpretations. | The triangle and parallelogram laws of <br> addition. <br> Parallel vectors. |
| 9.4 | Understand and use position <br> vectors; calculate the <br> distance between two points <br> represented by position <br> vectors. | $\overrightarrow{O B}-\overrightarrow{O A}=\overrightarrow{A B}=\mathbf{b}-\mathbf{a}$ <br> The distance $d$ between two points <br> $\left(x_{1}, y_{1}\right)$ and $\left(x_{2}, y_{2}\right)$ is given by <br> $d^{2}=\left(x_{1}-x_{2}\right)^{2}+\left(y_{1}-y_{2}\right)^{2}$ |
| 9.5 | Use vectors to solve <br> problems in pure <br> mathematics and in context, <br> (including forces). | For example, <br> finding position vector of the fourth corner <br> of a shape $(e . g$. parallelogram $A B C D$ with <br> three given position vectors for the corners <br> $A, B$ and $C$ |
| finding position vector of a point $C$ on a line |  |  |
| through $A$ and $B$ dividing $A B$ in a given |  |  |
| ratio, where position vectors of $A$ and $B$ are |  |  |
| given. |  |  |
| Contexts such as velocity, displacement, |  |  |
| kinematics and forces will be covered in |  |  |
| Paper 3, Sections $6.1,7.3$ and $8.1-8.4$ |  |  |

## Vector basics

Whereas a coordinate represents a position in space, a vector represents a displacement in space.

- A vector has 2 properties:
- Direction
- Magnitude (i.e. length)

If $P$ and $Q$ are points then $\overrightarrow{P Q}$ is the vector between them.

- If two vectors $\overrightarrow{P Q}$ and $\overrightarrow{R S}$ have the same magnitude and direction, they're the same vector and are parallel.
- $\overrightarrow{A B}=-\overrightarrow{B A}$ and the two vectors are parallel, equal in magnitude but in opposite directions.
- Triangle Law for vector addition:

$$
\overrightarrow{A B}+\overrightarrow{B C}=\overrightarrow{A C}
$$

The vector of multiple vectors is known as the resultant vector. (you will encounter this term in Mechanics)

- Vector subtraction is defined using vector addition and negation:

$$
a-b=a+(-b)
$$

- The zero vector $\mathbf{0}$ (a bold 0), represents no movement.

$$
\overrightarrow{P Q}+\overrightarrow{Q P}=\mathbf{0}
$$

$\ln 2 \mathrm{D}: \mathbf{0}=\binom{0}{0}$

- A scalar is a normal number, which can be used to 'scale' a vector.
- The direction will be the same.
- But the magnitude will be different (unless the scalar is 1 ).
- Any vector parallel to the vector $\boldsymbol{a}$ can be written as $\lambda \boldsymbol{a}$, where $\lambda$ is a scalar.

The implication is that if we can write one vector as a multiple of another, then we can show they are parallel.

## Example

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$P Q R S$ is a parallelogram.
$N$ is the point on $S Q$ such that $S N: N Q=3: 2$
$\overrightarrow{P Q}=\mathbf{a} \quad \overrightarrow{P S}=\mathbf{b}$
(a) Write down, in terms of $\mathbf{a}$ and $\mathbf{b}$, an expression for $\overrightarrow{S Q}$.
(b) Express $\overrightarrow{N R}$ in terms of $\mathbf{a}$ and $\mathbf{b}$.

## Test your understanding

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Diagram NOT accurately drawn
$O A B$ is a triangle.

$$
\overrightarrow{O A}=\mathbf{a}
$$

$$
\overrightarrow{O B}=\mathbf{b}
$$

(a) Find $\overline{A B}$ in terms of $\mathbf{a}$ and $\mathbf{b}$.
$P$ is the point on $A B$ such that $A P: P B=3: 1$
(b) Find $\overline{O P}$ in terms of $\mathbf{a}$ and $\mathbf{b}$.

Give your answer in its simplest form.

